

## Math 204 Linear Algebra, Homework 5

Name:

Due: Friday, March 5th, 2010

You should print these pages out two-sided (if possible) to save paper, money, and trees. Staple your sheets together. Write your answers clearly.

---

1. Find a basis of  $\mathbb{R}^3$  that contains the vector  $(1, 2, 3)$ . Explain your work.

$$B = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right\}$$

Need to show that  $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 3 \end{bmatrix}$  is invertible.

$\text{ref}(A) = I_3$  (check this).

2. (a) Show that the collection of vectors in  $\mathbb{R}^3$  that satisfy  $2x_1 + 3x_2 - 4x_3 = 0$  is a subspace of  $\mathbb{R}^3$ .  
Construct a basis for this space.
- (b) Generalize your answer to the subspace  $ax_1 + bx_2 + cx_3 = 0$ .

$$(a) \quad V = \left\{ \vec{x} \in \mathbb{R}^3 \mid \vec{x} \cdot \begin{pmatrix} 2 \\ 3 \\ -4 \end{pmatrix} = 0 \right\} = \left\{ \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} \right\}^\perp$$

hence  $V$  is a subspace

$$\mathcal{B} = \left\{ \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 4/3 \\ 1 \end{pmatrix} \right\}$$

(Check this is a basis)

- (b) if  $a=b=c=0$ , then  $V = \mathbb{R}^3$   
if two of them are zero (say  $b=c=0$ ) then

$$\mathcal{B} = \left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

if exactly one is zero (say  $c=0$ ), then

$$\mathcal{B} = \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -b/a \\ 1 \\ 0 \end{pmatrix} \right\}$$

3. Let  $\vec{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$ ,  $\vec{v}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ ,  $\vec{v}_3 = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$  and  $\vec{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ .

(a) Express  $\vec{v}$  as a linear combination of the vectors  $\vec{v}_1, \vec{v}_2, \vec{v}_3$ .

(b) Check that  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  a basis for  $\mathbb{R}^3$ .

(c) The linear transformation  $T$  has the matrix  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & 2 & -1 \end{bmatrix}$  in the standard basis. Find the matrix of  $T$  in the basis of the previous part.

$$(a) \quad \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = c_1 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = S \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

$$S^{-1} = \begin{bmatrix} -1 & 3 & -1 \\ 1 & -4 & 2 \\ 1 & -2 & 1 \end{bmatrix}, \text{ so } \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = S^{-1} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix}$$

(check)

(b) Since  $S$  is invertible,  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is a basis

$$(c) \quad A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & -1 \\ 0 & 2 & -1 \end{bmatrix} \quad B = S^{-1} A S = \begin{bmatrix} 3 & -1 & 3 \\ -4 & 0 & -4 \\ -2 & 0 & -1 \end{bmatrix}$$

4. In this exercise you are being asked to give a proof of some of the facts that we mentioned in class. In class we proved the following theorem:

**Theorem 1.** Let  $W$  be a subspace of  $\mathbb{R}^n$ . If  $\{\vec{w}_1, \dots, \vec{w}_m\}$  is a spanning set for  $W$  and  $\{\vec{v}_1, \dots, \vec{v}_p\}$  is a linearly independent set in  $W$ , then  $p \leq m$ .

Use this theorem to prove the following facts.

- Every subspace of  $\mathbb{R}^n$  is finite-dimensional.
- Any two bases of a subspace  $W$  have the same number of vectors. (this is what allows us to define dimension in an unambiguous way).
- If  $V$  and  $W$  are subspaces of  $\mathbb{R}^n$ , and  $V \subseteq W$ , then  $\dim(V) \leq \dim(W)$ .

We begin by proving the following:

Thm: If  $W$  is finite dimensional,  $V$  is finite-dimensional and  $V \subseteq W$ , then  $\dim(V) \leq \dim(W)$ .

Proof induction on  $\dim(W)$ .

base case:  $\dim(W) = 1$ . Then  $V = \{\vec{0}\}$  or  $V = W$  so we're done

Induction: assume true for  $\dim(W) = n$  and assume

$V \subseteq W$ ,  $\dim(W) = n+1$ . If  $V = \{\vec{0}\}$ , then  $\dim(V) = 0 < n+1$

Otherwise choose  $\vec{w} \in V$ ,  $\vec{w} \neq \vec{0}$

(a) Follows from above by setting  $\mathbb{R}^n = W$ .

(b) Both bases are lin. indep and spanning

4

(c) Follows from (a) and above

5. Let  $V, W$  be subspaces of  $\mathbb{R}^n$ . Define  $V + W = \{\vec{v} + \vec{w} : \vec{v} \in V, \vec{w} \in W\}$ .

(a) Show that  $V + W$  is a subspace.

(b) Show that  $\dim(V + W) + \dim(V \cap W) = \dim(V) + \dim(W)$ . (If you have taken a probability class this should look very familiar.) Hint: start with a basis of  $V \cap W$  and extend it to bases of  $V$  and  $W$ .

$$(a) \quad \vec{0} \in V, \vec{0} \in W, \text{ so } \vec{0} = \vec{0} + \vec{0} \in V + W.$$

$$\text{If } \vec{x}, \vec{y} \in V + W, \text{ then } \vec{x} = \vec{v}_1 + \vec{w}_1 \text{ and } \vec{y} = \vec{v}_2 + \vec{w}_2.$$

$$\text{So } c\vec{x} + \vec{y} = \underbrace{(c\vec{v}_1 + \vec{v}_2)}_{\in V} + \underbrace{(c\vec{w}_1 + \vec{w}_2)}_{\in W} \in V + W$$

(b) let  $\{u_1, \dots, u_p\}$  be a basis for  $V \cap W$ .

Extend this to a basis  $\{u_1, \dots, u_p, v_1, \dots, v_m\}$  for  $V$

and a basis  $\{u_1, \dots, u_p, w_1, \dots, w_k\}$  for  $W$ .

Claim:  $\{u_1, \dots, u_p, w_1, \dots, w_k, v_1, \dots, v_m\}$  is a basis for  $V + W$ . Spanning is straight forward

$$\text{Lin indep: If } \underbrace{c_1 u_1 + \dots + c_p u_p}_{\vec{u}} + \underbrace{d_1 v_1 + \dots + d_m v_m}_{\vec{v}} + \underbrace{b_1 w_1 + \dots + b_k w_k}_{\vec{w}} = \vec{0}$$

then

$\vec{u} + \vec{v} = -\vec{w} \in V \cap W$ . Hence,  $\vec{w} = \vec{0}$  (note  $\vec{w}$  is not in  $V \cap W$ ). So  $\vec{w} = \vec{0} = \vec{u} + \vec{v}$ . Since

$\{w_1, \dots, w_k\}$  lin indep we get  $b_1 = \dots = b_k = 0$ .

Since  $\{u_1, \dots, u_p, v_1, \dots, v_m\}$  lin indep  $c_1 = \dots = c_p = d_1 = \dots = d_m = 0$

6. **Bonus problem** Suppose that  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is a function that preserves inner products, i.e.,  $T(\vec{x}) \cdot T(\vec{y}) = \vec{x} \cdot \vec{y}$  for all  $\vec{x}, \vec{y} \in \mathbb{R}^n$ . Does it follow that  $T$  is necessarily linear? What if  $T$  preserves distances?